

*Status of the Claims*

The listing of claims will replace all prior versions, and listings of claims in the application.

1. (previously presented) A system for capturing biometric data, comprising:
  - a non-planar prism comprising a substantially conical portion, a top portion, and a planar portion, the non-planar prism configured to be illuminated by a light source; and
  - a scanning optical system configured to capture image data of a print area of a hand of a person interacting with the substantially conical portion of the non-planar prism, such that the top portion is located between a thumb of the hand and an index finger of the hand, the thumb of the hand interacts with a first side of the substantially conical portion, and the fingers of the hand interact with a second, opposite side of the substantially conical portion during the capture of the image data;wherein the image data represents substantially all of the print area of the hand of the person, while the hand is stationary on the substantially conical portion of the non-planar prism.
2. (currently amended) The system of claim 1, wherein:
  - the substantially conical portion is configured to receive the print area of the hand of the person on a first, outside surface and to totally internally reflect light beams from the light source from a second, inside surface; and
  - the planar portion is coupled at an angle to the substantially conical portion through which the totally internally reflected light exits to be received by the scanning optical system.
3. (original) The system of claim 1, wherein the scanning optical system rotates around an axis of symmetry of the non-planar prism.
4. (original) The system of claim 1, wherein an element in the scanning optical system rotates a received image to perform the scanning.

5. (original) The system of claim 4, wherein the element is an image rotator element selected from the group consisting of a dove prism and a Pachan prism.

6. (original) The system of claim 1, wherein the scanning optical system moves along an arcuate path to capture radial scan line images transmitted through a base of the non-planar prism.

7. (previously presented) The system of claim 1, further comprising a processing system that converts the captured image data into transmittable information that is transmitted by a communications system.

8. (original) The system of claim 7, wherein the communications system comprises a FIREWIRE system.

9. (original) The system of claim 1, further comprising a processing system comprising a means for converting the captured image data from a first coordinate system into image data in a second coordinate system.

10. (original) The system of claim 9, wherein the first coordinate system is a surface of the non-planar prism and the second coordinate system is a planar coordinate system.

11. (original) The system of claim 1, further comprising an encoder configured to encode a position of the scanning optical system and to generate encoder data.

12. (original) The system of claim 1, wherein the scanning optical system comprises a control system configured to control a motor, belt, and pulley system.

13. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture a palm print image as the image data.

14. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture palm print and fingerprint images as the image data.

15. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture both palm print images as the image data.

16. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture both sets of palm print images and fingerprint images as the image data.

17. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture palm print, fingerprint, and target images as the image data.

18. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture a writer's palm image as the image data.

19. (original) The system of claim 1, wherein the non-planar prism and the scanning optical system are configured to capture a writer's palm and fingertip images as the image data.

20. (previously presented) The system of claim 1, wherein the light source is positioned to direct light from the light source to an inside surface of the substantially conical portion of the non-planar prism configured to totally internally reflect the light so that the light exits the planar portion of the non-planar prism.

21. (previously presented) The system of claim 1, wherein:  
the substantially conical portion has a surface area sized to receive the print area of the hand or both print areas of both hands of the person; and  
the planar portion is located at an angle with respect to the substantially conical portion and has a smaller surface area than the curved portion.
22. (original) The system of claim 1, wherein the light source is positioned within a cylindrical opening running along an axis of symmetry of the prism.
23. (previously presented) The system of claim 1, wherein the light source is positioned proximate a chamfered edge of the prism.
24. (original) The system of claim 1, wherein the system further comprises first and second processing systems that are coupled via a communications system via at least one of an Internet, an Intranet, a hardwire connection, a wireless system, a FIREWIRE transceiver, a USB transceiver, and an Ethernet.
25. (original) The system of claim 1, further comprising an air treatment system positioned proximate the non-planar prism.
26. (previously presented) The system of claim 25, wherein the air treatment system performs one of heating, sanitizing, ionizing, and dehumidifying of the non-planar prism and/or the print area of the hand of the person.
27. (previously presented) A system for capturing biometric data comprising:  
a non-planar prism configured to totally internally reflect light from a substantially conical portion of the non-planar prism, such that the totally internally reflected light exits a planar portion of the non-planar prism; and  
an image capturing system that receives the totally internally reflected light and generates image data therefrom of a print area of a hand of a person interacting with opposite sides of the substantially conical portion of the non-planar prism, wherein the hand is configured to be positioned using a top portion of the non-planar prism,  
wherein the image data represents substantially all of the print area of the

hand of the person, while the hand is stationary on the substantially conical portion of the non-planar prism.

28. (original) The system of claim 27, wherein the image capturing system comprises a stationary lens and a stationary large area array.

29. (previously presented) The system of claim 28, wherein the lens is sized to capture all light leaving the non-planar prism that has been totally internally reflected from a section of the non-planar prism proximate an area in which the print area of the hand of the person interacted with the non-planar prism.

30. (original) The system of claim 27, wherein the image capturing system rotates around an axis of symmetry of the non-planar prism.

31. (cancelled)

32. (previously presented) The system of claim 1, wherein the non-planar prism comprises a conical prism.

33. (cancelled)

34. (previously presented) The system of claim 27, wherein the non-planar prism comprises a conical prism.

35-36 (cancelled)

37. (previously presented) The system of claim 1, wherein the top portion includes a guide extending therefrom, such that the guide is used to properly position the hand on the substantially conical portion.

38. (previously presented) The system of claim 27, wherein the top portion includes a guide extending therefrom, such that the guide is used to properly position the hand on the substantially conical portion.

39. (new) The system of claim 17, wherein the target images are configured to be obtained from a calibration target associated with the non-planar prism.

40. (new) The system of claim 39, wherein captured image data from the calibration target is configured to be used for subsequent proper displaying of the palm print and fingerprint image.

41. (new) The system of claim 39, wherein captured image data from the calibration target is configured to be used to determine quality of the palm print and fingerprint image.

42. (new) The system of claim 17, wherein image data from palm print, fingerprint, and target images are captured simultaneously, and stored together.